

DEPLOYMENT LOG for IceCube STRING # 73

DEI COTMENT	-	
Deployment Start: at ~ 7	:30+ on 1/1/07	
Deployment End: at	57 on 1/1/07	
Target depth (DOM60): 245	i 0 m Final∘depth:	2460*
+ see lost prope	For Final dyplb ante	
Position	First Shift	Second Shift
Shift lead	Torn Ham	Allowant
DOM install 1 (high)	- Jin Letshaw	
DOM install 2 (low)	- Red Mithou	
DOM supply 1 / DOM install 3	sur ledotion	
DOM supply 2 / floater	?•	
Winch operator (cable & tower)	Com comi	
Notary (logbook & photos)	Freija / Dangham)	Andrew 1 Down P
PTS (monitoring / sensors)	Freisa Descampo	Andre Morez
Support (optional)	/	/
Time o	of shift change:	
Summary/Comments:	1203	,5413
- pase pudable too de	pry 10m	
- Tudo broke broke	**	to had so d
	Continued Duy ast	
theller dets wel-	35 (d)	. 10.
- drapp in killer do	was broken	1/37



Hole Handover			
Drill data reviewed	;	, ,	
maximum drift in	x:	_ D plot	
maximum drift in	y:	_ plot	
maximum depth:_			grant A
☐ minimum radius:_		□ plot	
☐ plot of predicted r	adius vs d	epth and time	
☐ Hole dimensions veri	fied		Time: ₮ඎ
Drill Lead:			
		ne / signature / date	
Deployment Lead: _	Jan San San Jan San Ja	4 / 10/1/1	
,	nan	ne / signature / date	
	Hando	ver complete	
	liata	Logging	
Some of the second seco		Logging ot applicable)	The second secon
☐ Logger drop started	Time:	Speed:	gare to the
☐ Logging started	Time:	Speed:	
☐ Logging ended	Time:		
☐ Estimated hole lifeting			and the second
► Must reach targ	jet depth	by or	1



Deployment Startup		
Time: 7 30 cm		
☐ Cable winch anchored and ☐ operational ☐ Tower winch operational ☐ Tie off verified ☑ Yellow rope verified		
Deployment monitoring system (PTS) operational DDB# Pressure sensors on hand: Paro and Keller, with backups Laser ranger, tape measure (metric) on hand		
Bleeder string installed (on quad connectors inside cable reel drum)		
Uphole pressure system on hand: Setra sensor and cable		
 ☑ DOMs placed in racks ☑ Weight stack on hand: weights (5) and 2 m cable ☑ 17 m string extension steel cable on hand 		
Safety checks complete (□ 1 st shift □ 2 nd shift) □ □ Crew safety briefing □ □ E-stop locations identified □ □ TOS evacuation procedures reviewed □ □ Mustering point identified □ □ Snow mobile driver(s):		
☐ CPR trained:		
☐ Food runners: call galley at 65521		
☐ End of Main Cable brought into TOS and secured		
Cable end attachments		
Measure well depth: 70.357 (Nowwell 3x) Weights (5) attached		
Weight cable attached (weight stack complete) Time: 46 100		



Photos: DOM ids (♥ long ♥ short); connectors (□ long □ short)		
DOM position 6 (T, Long)	0	DOM id: TP <u>6 y 44 5</u> g
	e connected to weight stack onnected to 17 m steel cable view	Payout: 4.58
DOM position 5	9	DOM id: UP <u>6y445</u> 8
(U, Short)	Cable mark: MA	- /
Top shackle co Main cable end	e connected to 17 m cable onnected to Yale grip d taped to 17 m steel cable entation whole view	Δ(59-60): 17 160 (use laser ranger)
Breakout 30		Time: <u>40.054m</u>
		Depth:
1 .es	O-ring in place and labed lubed lubed lubed	Payout <u>92.65</u>
- ShortDOM ☐ connector O-ring in place and ☐ kubed ☐ breakout O-ring in place and ☐ lubed ☐ connected		
Loose pigtails	taped to cable	
Paro Serial #: 10465€ Nipple on □ off □ Connected □ Operational □ Air pressure [PSI]: 9.16 □ Cable mark: № □ Distance to DOM59: 0.910		
√All clear to lower cable ⊚		
V∕All clear to lower cable ⊚		



Photos: DOM ids (long short); connectors	(□ long □ sho	ort)
DOM position 58		DOM id:	[]
(T, Long)	Cable mark: ØÇ17		AP4P0060
□ Bow OK → □ cl	ected at link # 19	Δ(58-59): <u>4</u> 6	
DOM position 57		DOM id:	UP691314
(U, Short)	Cable mark: \$\\delta \omega 33\$		
\square Bow OK $\rightarrow \square$ ch	ected at link # 19	Δ(57-58): <u>46</u>	960
Breakout 29			Time:
		Now_	
- LongDOM		Last b/o _	u
	ring in place and □ lubed	Δt [min]	
	ng in place and □ lubed	, .	Depth:
□ connected			
- ShortDOM		Payout_	
□ connector O-1	ring in place and □ lubed ng in place and □ lubed		
☐ Loose pigtails tap	ped to cable		

☐ All clear to lower cable ☺



String 73

Photos: DOM ids	(☐ long ☐ short); connectors	s (long short)
DOM position 56		DOM id: TP 5 £ \$ 695
\Box Bow OK $\rightarrow \Box$ (nected at link #ici	Δ(56-57): 10.9
DOM position 55 (U, Short)	Cable mark: 67	DOM id: UP <u>691366</u>
\Box Bow OK $\rightarrow \Box$ c	nected at link #	Δ(55-56): <u>΄΄</u>
Breakout 28		Time:
 □ breakout O-1 □ connected - ShortDOM □ connector O □ breakout O-1 □ connected 	9-ring in place and □ lubed ring in place and □ lubed 9-ring in place and □ lubed ring in place and □ lubed ring in place and □ lubed	Now 16 32 Last b/o At [min] Depth: Paro 881 Payout 365
☐ Loose pigtails ta	iped to cable	
	☐ All clear to lower cabl	le ⊚



Photos: DOM ids (long ☐ short); connector	s (□ long □ short)
DOM position 54	Cable mark:	DOM id: TP 6P1343
\square Bow OK $\rightarrow \square$ ch	onnected cted at link #	Δ(54-55) : <u>√</u>
DOM position 53 (U, Short)	Cable mark:	DOM id: UP <u>6P1376</u>
\square Bow OK $\rightarrow \square$ cl	cted at link #	Δ(53-54): <u>↓૽,</u>
Breakout 27		Time:
□ breakout O-ri□ connected- ShortDOM□ connector O-r	ring in place and □ lubed ng in place and □ lubed ring in place and □ lubed ng in place and □ lubed bed to cable	Now Cast S Last b/o At [min] Depth: Paro 122 Payout 126
	☐ All clear to lower cal	ole 😊



Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)		
DOM position 52		DOM id: TP57109
(T, Long) Ca	ble mark: 118	
 □ Bottom shackle conn □ Top clutch connected □ Bow OK → □ clutch Photos: □ phi orientation 	d at link #/^/ n zip tied	Δ(52-53): 16.4
DOM position 51		DOM id: UP6P1436
\	ble mark: <u>35</u>	
☐ Bottom shackle conn ☐ Top clutch connected ☐ Bow OK → ☐ clutch Photos: ☐ phi orientation	d at link # n zip tied	Δ(51-52): <u> 6 9</u>
Breakout 26		Time:
- LongDOM □ connector O-ring □ breakout O-ring i □ connected - ShortDOM □ connector O-ring	in place and □ lubed ito cable	Now 10:55 Last b/o At [min] Depth: Paro 156 Payout 154
	All clear to lower cal	ble ☺



Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)		
DOM position 50		DOM id: TP 681347
(T, Long)	Cable mark:	
☐ Bow OK → ☐ cl Photos: ☐ phi orien	ected at link #	Δ(50-51): 16.5 Vertical distance:
DOM position 49 (U, Short)	Cable mark: 169	DOM id: UP 67 4442
 □ Bottom shackle of □ Top clutch connected □ Bow OK → □ cl Photos: □ phi orient 	connected ected at link #	Δ(49-50): 16.9 Vertical distance:
Breakout 25		Time:
□ breakout O-r.□ connected- ShortDOM□ connector O-	ring in place and \Box lubed ing in place and \Box lubed ring in place and \Box lubed ing in place and \Box lubed ped to cable	Now 11:06 Last b/o At [min] Depth: Paro 190 Payout 188
	☐ All clear to lower cat	ole ©



Photos: DOM	ids (☐ long ☐ short); connectors	$(\Box \text{ long } \Box \text{ short})$
DOM position	48	DOM id: TP <u>(ሃ</u> //365
(T, Long)	Cable mark:	
☐ Bow OK →	ckle connected connected at link # 9 clutch zip tied orientation whole view	Δ(48-49): 16. 9
DOM position	47	DOM id: UP <u>(4)358</u>
(U, Short)	Cable mark: ৃ 🚧 ८ 🔠	- ;
☑ Bottom shad☑ Top clutch o☑ Bow OK →	ckle connected connected at link # clutch zip tied orientation	Δ(47-48): <u>/ ε.</u> ?
Breakout 24		Time:
☐ breakou ☐ connecte ☐ breakou ☐ breakou ☐ breakou ☐ connecte	or O-ring in place and □ lubed t O-ring in place and □ lubed	Now //:/7 Last b/o Δt [min] Depth: Paro 22/1 Payout 22/1
	□ All clear to lower cab	
1	i Ali Geal to lower cat	/



Photos: DOM id	s (long short); connectors	(□ long □ short)
DOM position 4	6	DOM id: TP
(T, Long)	Cable mark: 214	
\square Bow OK $\rightarrow \square$	nnected at link #	Δ(46-47): 17
DOM position 4	5	DOM id: UP <u>62318</u>
(U, Short)	Cable mark:	- applife comment on a second
\square Bow OK $\rightarrow \square$	nnected at link #	Δ(45-46):
Breakout 23		Time:
		Now_11-2 8
- LongDOM	0'''	Last b/o
	O-ring in place and ☐ lubed O-ring in place and ☐ lubed	Δt [min] Depth:
connected	-ring in place and in label	Paro <u> </u>
		Payout 255
	O-ring in place and □ lubed place and □ lubed	
☐ Loose pigtails	taped to cable	
	□ Ali alaar ta lawar aab	lo o
	☐ All clear to lower cab	IE ⊎



Photos: DOM ids (☑¹long ☐ short); connectors (☐ long ☐ short)		
DOM position	44	DOM id: TP 674449
(T, Long)	Cable mark:_ 공53	
✓ Top clutch of✓ Bow OK →	ckle connected connected at link # Connected at link # Clutch zip tied crientation \(\text{\ti}\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\text{\texi{\text{\text{\text{\text{\text{\texi{\text{\text{\texi\texi{\text{\text{\text{\text{\texi}	Δ(44-45): 16.4
DOM position	43	DOM id: UP 68 1360
(U, Short)	Cable mark: 276	
☐ Top clutch of Bow OK →	ckle connected connected at link # clutch zip tied orientation <= whole view	Δ(43-44):
Breakout 22		Time:
□ breakou □-connecte	or O-ring in place and \Box lubed t O-ring in place and \Box lubed ed	Now 13 53 Last b/o Δt [min] Depth: Paro 245 Payout 289
	or O-ring in place and \square lubed to O-ring in place and \square lubed ed	
☐ Loose pigta	ils taped to cable	
bak	From Junior 12'40	
	□ All clear to lower cab	ole ⊙



Photos: DOM ids (∃ long ✓ short); connectors	(□ long □ short)
DOM position 42	Cable mark:	DOM id: TP 5 P 0 5 6 9
(T, Long)	Cable mark:	
\square Bow OK $\rightarrow \square$ cl	ected at link #	Δ(42-43) : 16-9
DOM position 41 (U, Short)	Cable mark: 30박	DOM id: UP <u>4P0272</u>
\square Bow OK $\rightarrow \square$ cl	ected at link #_ 20_	Δ(41-42): 16.9
Breakout 21		Time:
		Now_13103
- LongDOM		Last b/o
	ring in place and lubed	Δt [min]
□ breakout O-r	ing in place and □ lubed	Depth: Paro _3⊋4
Connected		Payout 323
- ShortDOM		
	ring in place and □ lubed ing in place and □ lubed	
Loose pigtails ta	ped to cable	
	☐ All clear to lower cab	le ⊚



Photos: DOM ids	s (onectors	(□ long □ short)
DOM position 40)	DOM id: TP 6 P 14 09
(T, Long)	Cable mark: 331	
Bow OK → □	nected at link #_14	Δ(40-41): 16.9
DOM position 39)	DOM id: UP 6P1428
(U, Short)	Cable mark: 337	
\square Bow OK $\rightarrow \square$	nected at link #	Δ(39-40): 16 1
Breakout 20		Time:
□ breakout O□ connected- ShortDOM□ connector O	O-ring in place and lubed lube	Now 13 13 Last b/o At [min] Depth: Paro 363 Payout 356
	☐ All clear to lower cab	ole ⊙





Photos: DOM ids (long short); connectors	s (□ long □ short)
DOM position 38		DOM id: TP 470035
(T, Long)	Cable mark: <u> </u>	
\square Bow OK $\rightarrow \square$ cl	ected at link # 19	Δ(38-39): <u>}</u>
DOM position 37		DOM id: UP 5P1016
(U, Short)	Cable mark: 371	<u> </u>
☐ Bow OK → ☐ cl	ected at link #	Δ(37-38): <u>16.4</u>
Breakout 19		Time:
 □ breakout O-ri □ connected - ShortDOM □ connector O-i □ breakout O-ri □ connected 	ring in place and □ lubed ng in place and □ lubed ring in place and □ lubed ng in place and □ lubed	Now 13 22 Last b/o Δt [min] Depth: Paro 398 Payout 390
☐ Loose pigtails tap	ed to cable	
	□ All clear to lower cab	Ne ⊙



Photos: DOM ids	s (\square long \square short); connectors	(□ long □ short)
DOM position 3	5 0 2	DOM id : TP <u>5 P 0 9 0 7</u>
(T, Long)	Cable mark: 389	
\Box Bow OK $\rightarrow \Box$	nnected at link #	Δ(36-37): 16 4
DOM position 39 (U, Short)	5 Cable mark: 405	DOM id: UP 420306
\square Bow OK $\rightarrow \square$	nnected at link # 19	Δ(35-36) : 17.6
Breakout 18		Time:
☐ breakout C ☐ connected	O-ring in place and ☐ lubed I-ring in place and ☐ lubed	Now 13 33 Last b/o Δt [min] Depth: Paro 43 2 Payout 434
	O-ring in place and □ lubed or lubed or lubed or lubed	
☐ Loose pigtails	taped to cable	
Put two Keller	rs (one is for backup) in bucke	t of water/ice mix
	⊡ All clear to lower cab	ole ⊚



Photos: DOM ids	(long short); connectors	s (□ long □ short)
DOM position 34	4.50	DOM id: TP 5P0709
(T, Long)	Cable mark: 433	
\Box Bow OK $\rightarrow \Box$	nected at link #	Δ(34-35) : 17.0
DOM position 33 (U, Short)	Cable mark: 439	DOM id : UP <u>3P05</u> 26
\square Bow OK $\rightarrow \square$	nected at link #	Δ(33-34): <u>17.0</u>
Breakout 17		Time:
□ breakout O-□ connected- ShortDOM□ connector O	O-ring in place and □ lubed bring in place and □ lubed oring in place and □ lubed bring in place and □ lubed aped to cable	Now 13 : 43 Last b/o Δt [min] Depth: Paro 465 Payout 456
	☑ All clear to lower cab	ole ©



Photos: DOM ids	s (Tlong Tshort); connectors	(□ long □ short)
DOM position 3		DOM id: TP 691423
(T, Long)	Cable mark: 457	
	nnected at link # 19	Δ(32-33) : 16.4
DOM position 3 (U, Short)	1 Cable mark:473	DOM id: UP <u>SP079</u> 0
☑ Bow OK → 🛭	nnected at link #	Δ(31-32): 16 4
Breakout 16		Time:
□ breakout C□ connectedShortDOM□ connector	O-ring in place and lubed taped to cable	Now 13.53 Last b/o At [min] Depth: Paro SOO Payout 491
	B'All clear to lower cab	ole ©



\$		
Photos: DOM ids	$(\Box \text{ long } \Box \text{ short}); \text{ connectors}$	(□ long □ short)
DOM position 30		DOM id: TP 6P (739)
(T, Long)	Cable mark: 490	
\square /Bow OK $\rightarrow \square$ (ected at link # 19	Δ(30-31): 169
DOM position 29 (U, Short)	Cable mark: 507	DOM id: UP <u>6у 4444</u>
\square Bow OK $\rightarrow \square$ (nected at link #	Δ(29-30) : 16 9
Breakout 15		Time:
		Now 14:08
- LongDOM		Last b/o
	-ring in place and 🗆 lubed	Δt [min]
	ring in place and □ lubed	Depth:
□ connected		Paro <u>535</u>
CI DOM		Payout 525
	ring in place and □ lubed ring in place and □ lubed	
□ Loose pigtails to	aped to cable	
Thermistor I	Present Distance to DOM	29:
Keller 2	Connected Coperational Cable mark: <u>507</u> Constant	Air pressure [PSI]: 6.68
, ,,,	☐ All clear to lower cab	



Photos: DOM	ids (☐Íong ☐ short); connectors	s (□ long □ short)
DOM position	2B	DOM id : TP <u>5Y0199</u>
(T, Long)	Cable mark: 524	
Bow OK →	ckle connected connected at link # 19 clutch zip tied corientation	Δ(28-29): 16.9
DOM position	27	DOM id: UP5P0524
(U, Short)	Cable mark: 5 4	
Bottom shacTop clutch cBow OK →		Δ(27-28): 16.9
Breakout 14		Time:
		Now 14-13
- LongDOM		Last b/o
	or O-ring in place and \square lubed	Δt [min]
	t O-ring in place and lubed	Depth:
Connecte	ed	Paro <u>564</u>
G1 (DO) (Keller <u>\$48</u>
- ShortDOM		Payout 558
	or O-ring in place and \square lubed to the control of	
□ Loose pigtai	ils taped to cable	
	-	
	☑ All clear to lower cab	ole 😊



Photos: DOM ids (\subseteq long \square -short); connector	s (□ long □ short)
DOM position 26		DOM id : TP 6 P 1335
(T, Long)	Cable mark: 558	
\square Bow OK $\rightarrow \square$ cl	ected at link # 19	Δ(26-27): 16.9
DOM position 25 (U, Short)	Cable mark: 575	DOM id: UP 5 P10 52
\square Bow OK $\rightarrow \square$ cl	ected at link # 19	Δ(25-26) : 16.4
Breakout 13		Time:
		Now_14:27
- LongDOM		Last b/o
, -	ring in place and □ lubed	Δt [min]
☐ breakout O-ri	ing in place and I lubed	Depth:
connected		Paro 604
		Keller 603
- ShortDOM		Payout_592
	ring in place and □ lubed ing in place and □ lubed	
☐ Loose pigtails tap	ped to cable	
,		
	•	
	All clear to lower cal	ble ☺



Photos: DOM ids (☐ long ☐ short); connectors	(□ long □ short)
DOM position 24	DOM id : TP_674347
(T, Long) Cable mark: 592	
 Bottom shackle connected Top clutch connected at link # 19 Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(24-25): 17.0
DOM position 23	DOM id: UP 6P1370
(U, Short) Cable mark: <u>もい</u> と	
Bottom shackle connected Top clutch connected at link #9 Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view	Δ(23-24): 17 3
Breakout 12	Time:
	Now 14:37
- LongDOM	Last b/o
☐ connector O-ring in place and ☐ lubed	Δt [min]
☐ breakout O-ring in place and ☐ lubed	Depth:
☐ connected	Paro <u>63 8</u> Keller 682
- ShortDOM	Payout 626
☐ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☐ connected☐	Tayout
☐ Loose pigtails taped to cable	
⊡∕All clear to lower cab	le ⊚



Photos: DOM ids (long s	hort); connectors (☐ long ☐ short)
DOM position 22	DOM id : TP_6Y4303
(T, Long) Cable ma	rk: 626
Bottom shackle connected Top clutch connected at lin Bow OK → Clutch zip tic Photos: phi orientation	ed
DOM position 21	DOM id: UP 6 7 4 3 2 8
• · · · · · · · · · · · · · · · · · · ·	rk: 642
Bottom shackle connected Top clutch connected at lin Bow OK → Clutch zip tic Photos: □ phi orientation □ v	ed
Breakout 11	Time:
	Now 14.47
- LongDOM	Last b/o
☐ connector O-ring in pla	
□ breakout O-ring in plac□ connected	Paro 673
	Keller 7.3 9
- ShortDOM	Payout 660
☐ connector O-ring in pla ☐ breakout O-ring in plac ☐ connected	
☐ Loose pigtails taped to cab	e
TÁII cl	ear to lower cable ⊚



Photos: DOM ids (□ long □ short); connectors	(long sh	ort)
DOM position 20		DOM id:	TP 6P1325
(T, Long)	Cable mark: 659		
☐ Bow OK → ☐ c Photos: ☐ phi orier	ected at link #9	Δ(20-21): \	,
DOM position 19		DOM id:	UP 644368
(U, Short)	Cable mark: 676		
☐ Bow OK → ☐ c Photos: ☐ phi orier	ected at link #_19_	Δ(19-20): <u> </u>	
Breakout 10			Time:
]			THIIQ.
· -		Now_	14×57/
- LongDOM			
- LongDOM Gonnector O	-ring in place and □ lubed	Last b/o_	14557
- LongDOM □ connector O- □ breakout O-r	-ring in place and □ lubed ring in place and □ lubed	Last b/o _ Δt [min]_	Depth:
- LongDOM Gonnector O-	- -	Last b/o _ Δt [min]_ Paro _	Depth: 706
- LongDOM □ connector O- □ breakout O-r □ connected	- -	Last b/o _ Δt [min]_ Paro _ Keller_	Depth: 706
- LongDOM Connector O- breakout O-r connected ShortDOM connector O-	- -	Last b/o _ Δt [min]_ Paro _ Keller_	Depth: 706
- LongDOM connector O- breakout O-r connected - ShortDOM connector O- breakout O-r	ring in place and □ lubed -ring in place and □ lubed ring in place and □ lubed	Last b/o _ Δt [min]_ Paro _ Keller_	Depth: 706



Photos: DOM ids	(☐ long ☐ short); connectors	(long short)
DOM position 18	}	DOM id: TP 5 P 0 8 8 7
(T, Long)	Cable mark: 693	
\square Bow OK $\rightarrow \square$	nected at link #9	Δ(18-19): 16.9
DOM position 17	,	DOM id: UP 644412
(U, Short)	Cable mark: 710	
	e connected nected at link #_\4	Δ(17-18): <u>16.9</u>
Breakout 9		Time:
☐ breakout O ☐ connected - ShortDOM ☐ connector (O-ring in place and □ lubed -ring in place and □ lubed O-ring in place and □ lubed -ring in place and □ lubed taped to cable	Now 15:07 Last b/o At [min] Depth: Paro 741 Keller 837 Payout 707
	All clear to lower cab	ole 😊



Photos: DOM ids (☐ long ☐ short); connectors	$(\Box \log \Box \text{ short})$
DOM position 16		DOM id: TP 6P1749
(T, Long)	Cable mark: 7)7	
\square Bow OK $\rightarrow \square$ c	ected at link # 19	Δ(16-17): 16.9
DOM position 15 (U, Short)	Cable mark: 744	DOM id: UP <u>69447</u> 8
\square Bow OK $\rightarrow \square$ c	ected at link # 19	Δ(15-16): <u>16</u>
Breakout 8		Time:
□ breakout O-r□ connected- ShortDOM□ connector O-	ring in place and □ lubed ing in place and □ lubed ring in place and □ lubed ing in place and □ lubed ped to cable	Now 15:17 Last b/o At [min] Depth: Paro 775 Keller 544 Payout 761
	☑∕All clear to lower cab	ole ⊚



Photos: DOM ic	ls (☐ long ☐ short); connectors	(□ long □ short)
DOM position 1		DOM id : TP <u>6Y443</u> 3
(T, Long)	Cable mark: 761	
\square Bow OK \rightarrow \square	tle connected onnected at link # clutch zip tied rientation	Δ(14-15): <u> 6.9</u>
DOM position 1 (U, Short)	Cable mark: 778	DOM id: UP 6 P 13 2 2
\square Bow OK $\rightarrow \square$	tle connected onnected at link # clutch zip tied rientation = whole view	Δ(13-14): 16.9
Breakout 7		Time:
☐ breakout (☐ connected ☐ connected ☐ connector	O-ring in place and □ lubed O-ring in place and □ lubed	Now 15 26 Last b/o Δt [min] Depth: Paro 810 Keller 881 Payout 796
	All clear to lower cat	ole ☺



Photos: DOM ids	(☐ long ☐ short); connectors	s (□ long □ short)
DOM position 12		DOM id: TP SP 0981
(T, Long)	Cable mark: 795	BOWN IC. IT STONE
(1, Long)	Cable maik.	
☑ Bottom shackle		
E	nected at link # 9	Δ(12-13) :17. <i>O</i>
$\square \text{ Bow OK} \to \square$	-	
Photos: Liphi orie	entation \square whole view	
DOM position 11		DOM id: UP 67 4430
(U, Short)	Cable mark:	<u> </u>
,		
☑ Bottom shackle		
_	nected at link # 20	Δ(11-12): <u>[6.5</u>
Bow OK → Bo	<u> </u>	
Photos. 🖹 pin one	entation whole view	
Breakout 6		Time:
		Now 15:45
- LongDOM		Last b/o
© connector C	O-ring in place and \Box lubed	Δt [min]
	ring in place and ☐ lubed	Depth:
□ connected		Paro <u>844</u>
		Keller 936
- ShortDOM	\ '	Payout 830
	oring in place and □ lubed	
☐ breakout O-☐ connected	ring in place and ☐ lubed	
Connected		
☐ Loose pigtails t	aped to cable	
1 0		
	☐ All clear to lower cat	ole 😊



Photos: DOM ids (s (□ long □ short)	
DOM position 10		DOM id: TP 6P	1327
(T, Long)	Cable mark: 8 2 8		
\boxtimes Bow OK $\rightarrow \boxtimes$ c	ected at link # 19	Δ(10-11) : <u>\7.0</u>	-
DOM position 9 (U, Short)	Cable mark: 8월5	DOM id: UP <u>6</u>	<u>′427</u> 4
\square Bow OK $\rightarrow \square$ c	ected at link #	Δ(9-10): 16.9	
Breakout 5		Time	
		Now 16:00	
- LongDOM		Last b/o	
© connector O-	ring in place and lubed	Δt [min]	
	ing in place and □ lubed	Deptl	า:
connected		Paro <u>880</u> Keller <u>966</u>	
G0			
- ShortDOM		Payout 864	
	ring in place and □ lubed ing in place and □ lubed		
☐ Loose pigtails ta	ped to cable		
	□ All cloor to lower coh	lo o	
	All clear to lower cab	ਸ ਦ 🙂	



Photos: DOM ids (☐ long ☐ short); connectors	s (□ long □ short)
DOM position 8	DOM id: TP 6 P 1751
(T, Long) Cable mark: 863	
Bottom shackle connected □ Top clutch connected at link # \ □ □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view	Δ(8-9): <u>16.9</u>
DOM position 7	DOM id: UP 5 P 0 794
(U, Short) Cable mark: \$7.9	
Bottom shackle connected ☐ Top clutch connected at link # ☐ Bow OK → ☐ clutch zip tied Photos: ☐ phi orientation ☐ whole view	Δ(7-8): 16 9
Breakout 4	Time:
	Now 16:12
- LongDOM	Last b/o
connector O-ring in place and lubed	Δt [min]
☐ breakout O-ring in place and ☐ lubed	Depth:
☐ connected	Paro <u>914</u>
GL- 4DOM	Keller 1016
- ShortDOM ☐ connector O-ring in place and ☐ lubed ☐ breakout O-ring in place and ☐ lubed ☐ connected	Payout <u>898</u>
☐ Loose pigtails taped to cable	
⊒ ∕All clear to lower cat	ole ⊚



Photos: DOM ids (☐ long ☐ short); connectors	(□ long □ short)
DOM position 6	DOM id: TP 6 P 1351
(T, Long) Cable mark: 896	
 ✓ Bottom shackle connected ✓ Top clutch connected at link # ✓ Bow OK → ☐ clutch zip tied Photos: ☐ phi orientation ☐ whole view 	Δ(6-7): 17.0
DOM position 5	DOM id: UP6P1336
(U, Short) Cable mark: 413	
Bottom shackle connected Top clutch connected at link # Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view	Δ(5-6): 16.9
Breakout 3	Time:
	Now_16-25
- LongDOM	Last b/o
Connector O-ring in place and lubed	Δt [min]
□ breakout O-ring in place and □ lubed□ connected	Depth: Paro_ 948
Connected	Keller 1055
- ShortDOM	Payout 431
☐ connector O-ring in place and ☐ lubed ☐ breakout O-ring in place and ☐ lubed ☐ connected	
☐ Loose pigtails taped to cable	
□ All clear to lower cab	



Photos: DOM ids (☐ long ☐ short); connectors	(□ long □ short)
DOM position 4		DOM id: TP 674277
(T, Long)	Cable mark: 431	
\square Bow OK $\rightarrow \square$ c	ected at link # 14	Δ(4-5): 17 ()
DOM position 3		DOM id: UP 694372
(U, Short)	Cable mark: 947	50
☐ Bow OK → ☐ c Photos: ☐ phi orien	ected at link # $\frac{18}{2}$	Δ(3-4): <u>7.0</u>
Breakout 2		Time:
☐ breakout O-1☐ connected - ShortDOM☐ connector O	ring in place and □ lubed	Now 16 40 Last b/o At [min] Depth: Paro 982 Keller 1102 65 Payout 965
	□ All aloor to lower ach	do o
İ	☐ All clear to lower cab	/IC 🙂



Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)					
DOM position 2	4 .	DOM id: TP <u>6P1329</u>			
(T, Long)	Cable mark: 964				
□ Bow OK → □ cl	cted at link # 19	Δ(2-3): 17 <i>O</i>			
DOM position 1		DOM id : UP <u>6P/33</u> 4			
(U, Short)	Cable mark:				
Bow OK → Cl	connected ected at link # 19	Δ(1-2): 16.9			
Breakout 1		Time:			
		Now 16:54			
- LongDOM		Last b/o			
	ring in place and \square lubed	Δt [min]			
	ng in place and ☐ lubed	Depth:			
⊡ connected		Paro 1017 Keller 1455			
- ShortDOM		Payout 949			
∃ connector O-1	ring in place and □ lubed ng in place and □ lubed				
☐ Loose pigtails tar	ped to cable				
No second Paro no n	nore				
	Group photo				
	⊡ All clear to lower cal	ole 😊			



Uphole Pressure Sensor (Setra)

After DOM1 is safely under the surface (> 50 m)

Time: 17:01

Stop	the	cable	winch
 ~~~			,

Lower Setra pressure sensor into hole

☐ Distance to Setra from floor:

Setra readout verified with monitoring system

Well depth from Setra:

□ Well depth from laser:  $\frac{55.74}{}$ 

If the two well depth measurements agree:

☐ Switch to Setra well depth in monitoring system

Time: 17:04

Now the String Drop begins

	icecube	String Deploy	inent Log		String 73
		Stri	ng Drop		
		The targe			
□ Swite	ch cable wir	nch to compute	r control		
☐ Spee	d:	Time:	Depth:		
☐ Spee	d:	Time:	Depth:		
□ Spee	d:	Time [.]	Depth:		
□ Spee	d:	Time:	Depth:		
□ Spee	d:	Time:	Depth:		
☐ Speed	d:	Time:	Depth:		
	Monitorin	(log on the fly –	1'		
Depth by Paro¹	Time	Well depth ¹	Depth by cable marks²	Depth by Payout¹	∆depth P-K¹
1000 m					
1500 m					
2000 m					
2100 m					
2200 m					
2300 m					
<u>2400 m</u>	18:51	52.2	2379	2403	
¹ Read off ra ² Cable mar		reen om p.4) (at DO	M59) – 17 m = _	(at ]	DOM60)
☐ Switc	ch to manua	l control @ 240	00 m		
	depth 420: 52. 440:	<u> </u>		·	
☑ Posit	ion string at	target depth of	f <b>2450</b> m	Time:	19.00

☑ String secured with Yale grip and anchor chain Time: 19.43



<b>Absolute</b>	depth v	vith bott	om Pa	KO.
(depth in $m$	<i>ieters</i> ar	nd pressi	ure in <i>F</i>	² SI)

☐ Distance from Paro to DOM6	0:		
$d_{Paro-DOM59} = \underline{\qquad} (from$	om p. 4)		
$d_{Paro-DOM60} = (d_{Paro-DOM59} +$	17) m = ← insert b	elow	
☐ Convert Paro pressure to strin	ng depth:		
K = 3.78151·10 ⁻⁶ /PSI	(compressibility of aerated water)	(n	use 6 decimals for exp's
Ambient pressure (from p. 4): Po	₀ =PSI → exp(-KF	-	_
Pressure reading (from screen): P	=PSI → exp(-KF	<b>)</b> =	<del>-</del>
Su	=		
		×	1.85947·10 ⁵
Paro depth in water →		=	m
Add distance to DOM60 (above) —			m
A	dd well depth →	+	m
De	epth of bottom DOM →	=	m

#### Final depth estimates

◄----- read off deployment screen ------>

Time: 19:43	Paro	Keller	Payout	Cable marks	
Reading	3430.86 PSI	3283 <b>PSI</b>	ə.446 <b>m</b>	2421 m	
Offset	9.67 PSI	6.68 PSI	ij <b>m</b>	17 <b>m</b>	
Well depth	52.2	m	TI CONTRACTOR OF THE STATE OF T		
Dist. to DOM60	18.10 m	527.69 m	This space is intentionally left blank		
DEPTH (DOM60)	2460.43	2906.7	2446	2438	

Time: 1954

Final depth (DOM60): 2460 *



Deployment Closeout				
☑ Log entries complete				
☑ String safely secured				
Hole covered and secured				
Equipment safely shutdown and secured				
□ Deployment data OK (in database)				
☑ Site cleanup				
☐ Deployment crew dismissed				
☑ String deployment complete				
Time: 19:57 Date: 1-1-07				
Shift Lead: 6 ary Hill 46 15 M				
Logger: Andres Morey Signature				
PTS Lead: Morey name / signature				
Deployment Manager:				
Safety Officer: name / signature				
IceCube On-ice Lead: Bob Marse name / signature				

## IceCube Deployment Monitoring Check Sheet (IDMCS)

#### Version 4.0 December 12, 2006

Kurt Woschnagg, UCB

#### General instructions

- ▶ Read through this entire document before deployment starts.
- ▶ Deployment monitoring is done with a computer (housed in the TOS) running drill/deployment monitoring software (by Chuck Rentmeesters) with a GUI for readout and manual inputs. All deployment sensor data and manual inputs are logged and saved on disk by this system.
- ► For each manual entry into the monitoring interface (marked ENTER below), also make a note in the logbook (marked Logbook below).
- For each entry in the logbook, include time and name (initials).
- ▶ Write down as much useful information you can think of (it will all be needed sooner or later).

#### Measurement instructions

- ▶ All vertical measurements are relative to the floor of the tower (not the lip of the kick board).
  - Measure well depth from this level.
  - Take cable mark readings at this level.
- ▶ The location of a DOM on a string (for distance measurements) is defined as the position of the center of the sphere (at the equator defined by the harness).
- ▶ When taking a cable mark reading, estimate the location to nearest cm (0.01 m) with closest cable marks and tape measure.
- ▶ The location of a Paro is defined at the bottom of its body (at the little hole with the nipple).
- ▶ The location of a Keller is defined at the row of holes in the black plastic nose cap.
- ► The distance between a pressure sensor and the nearest DOM is positive/negative if the unit is above/below the DOM.
- ▶ Well depth is measured with a laser ranger (if possible), or with a tape measure (if not).
- ▶ The unit used for all distances and depths during deployment is **meters**.

## Screen Tab: TO5 ▶ Deployment

#### ▶ Sensors/Graph

This is the main tab used during deployment monitoring. No input required on this tab.

Pressure/Depth of String

Current and ambient (air) pressures, and the corrected depths at DOM60. Spacing/Depth Comparison Difference in depth from pressure data. Should be stable during deployment!

Velocity

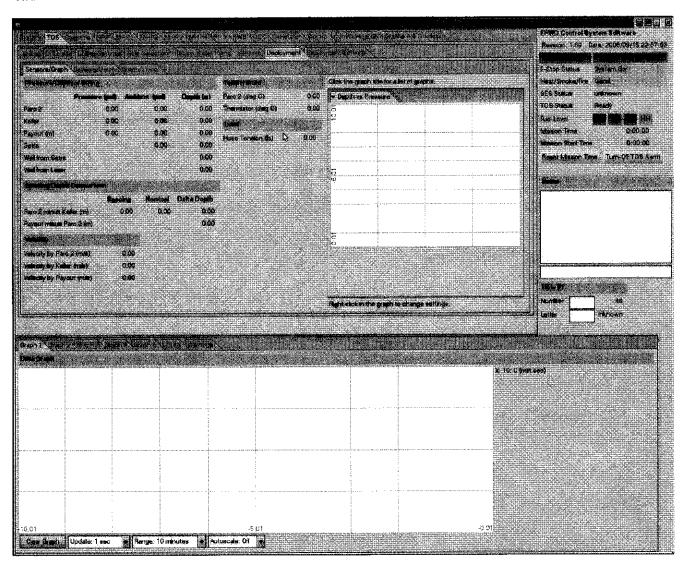
The deployment velocity calculated from recent pressure/payout readings.

**Temperature** 

Temperature readings.

Load

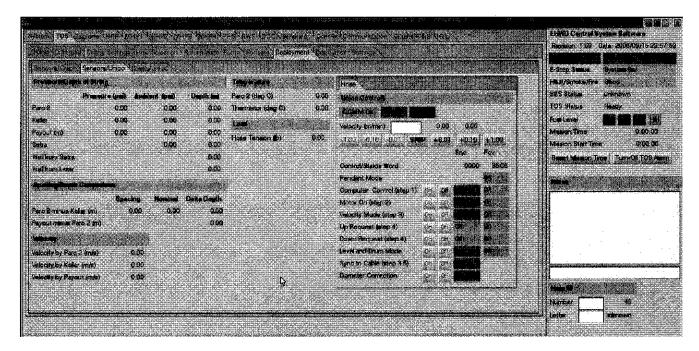
Cable tension from load cell data.



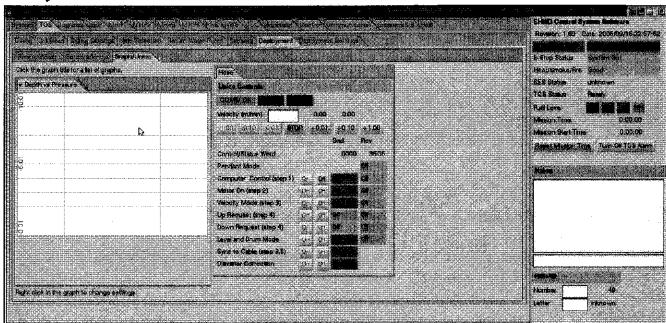
## Screen Tab: TOS ▶ Deployment

#### ► Sensors/Unico

This tab has the same data display as the main Sensors/Graph tab above, but instead of the graph window this tab has the controls for the Unico drive which controls the winch.



## ► Graph/Unico



### Screen Tab: TOS ➤ Deployment Settings

#### Settings

This is the main tab for entering information that is needed for a correct depth calibration of the pressure data. Make sure you understand what all the entries mean before deployment starts.

**Tower Mode** 

Click on "Deployment".

**Deployment Events** 

Click the appropriate button when one of the predefined events occurs (see list below). Select the correct DDB ID before deployment startup (needed for Keller calibration).

**DDB** Mode Payout at Tower

Reset payout when bottom DOM is at tower floor level. Well Depth Selection Select source of well depth used in depth calculation.

Ambient Pressures

Press "Get" when pressure sensor is attached to cable, or enter reading at that time.

**Nominal Spacing** 

Enter calculated distance between Paro and Keller.

**Distances** 

Enter calculated distances between Paro/Keller and DOM60, and well depth.

Setra Depth Calib.

Enter measured length of Setra cable, from floor to sensor. Set values for which alarm is to be sounded (optional).

Alarms

se Japan Well Depit. | Use Setta Will 1 0076 100 800.00

#### Deployment Events

Ctontum

- prateub	Chek when the deployment begins.
☐ Paro Attached	Click when the Paro is attached to the breakout and starts sending data.
🗌 Paro In Water	Click when the Paro reaches the water.
☐ Keller Attached	Click when the Keller is attached to the breakout and starts sending data.

☐ Keller In Water Click when the Keller reaches the water.

☐ String Drop Click when the String Drop phase begins, after all DOMs have been attached.

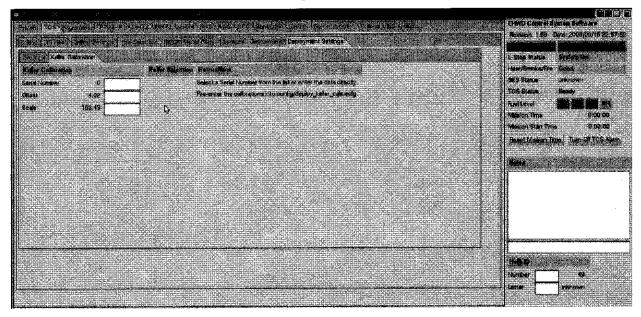
☐ Complete Click when the deployment ends (string is secured, etc).

Click when the deployment begins

## Screen Tab: TOS ➤ Deployment 5ettings

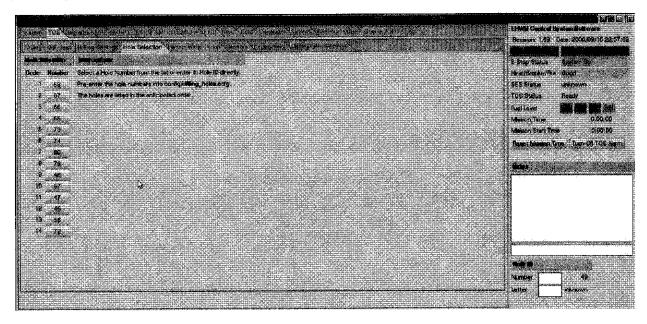
#### ▶ Keller Calibration

On this tab you select the Keller ID by clicking on the appropriate button. The correct (pre-programmed) calibration constants will then be used for the Keller pressure reading.



#### Screen Tab: TOS ▶ Hole Selection

On this tab you select the hole/string number, *either* by clicking on the numbered button on the left or by entering it in the "Hole ID" field in the lower right hand corner.



## Distances between devices calculate manually and enter on Deployment Settings tab

Distance between Paro and DOM60:	=
Distance between Keller and DOM60:	 =
Distance between Paro and Keller:	 =
Notes:	

There are 60 DOMs on every string.

The nominal spacing between DOMs is 17 m.

The nominal spacing between breakouts is 34 m.

Breakouts (1-30) and DOMs (1-60) are counted from the top.

The Keller is at breakout 15, just above DOM29.

The Paro is at breakout 30, just above DOM59.

(Fun Fact: There used to be a second Paro at breakout 1 on the first four strings)

#### Pressure conversions

		PSI	mH ₂ O	Atm
1 PSI	=	1	0.70	0.07
1 mH ₂ O	=	1.4	1	0.1
1 atm	=	14.7	10.3	1

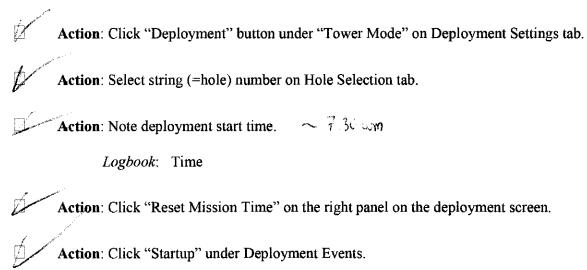
#### Check Sheet

	<b>STRING</b> # <u>73</u>	
DATE:		

## **Before Deployment**

,	Action: Locate laser ranger for well depth measurements.
$\dot{\mathbb{Z}}$	Action: Locate metric tape measure.
$\mathbf{t}'$	Action: Locate one Paro and one Keller, plus spares of each.
	Action: Locate bucket (for cooling of Keller sensor with water/ice mix).
$\mathbf{v}'$	Action: Fill bucket with snow and place in heated area to make slush.
	Action: Locate Setra uphole pressure assembly (sensor + cable).

## Deployment Startup





## IceCube String Deployment Monitoring

Action: Note DDB id number (1, 2, 3, or 4).

ENTER: DDB# (select button)

Logbook: DDB# 🔀

Action: Take a well den

Action: Take a well depth measurement with the laser ranger.

ENTER: Well depth [m] 70 357

Logbook: Well depth

Action: Reset Payout when DOM60 breaks the plane of the floor. a little but too limit (4 m)

**CLICK**: "Reset" button (Top of Hole Reset) on Deployment Settings ▶ Settings tab.

Logbook: Payout Start value

Action: Get cable mark reading at DOM59.

Logbook: Cable mark [m] WA

Action: Attach Paro at breakout #30. (This is called "Paro2" on the monitoring screen).

Logbook: Paro serial number 10463 6

Action: Click "Paro Attached" under Deployment Events.

Action: Measure distance between Paro location and nearest DOM.

Estimate distance to *bottom* DOM by adding n 17-meter segments (n should be 1 for the Paro since nearest DOM is #59).

**ENTER**: Distance [m] from Paro to bottom DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60

Action: Get cable mark reading at Paro.

Logbook: Cable mark [m]

Secretary W

8 of 11



## IceCube String Deployment Monitoring

	Action: Take Paro air pressure reading just before it breaks the water surface.
	ENTER: Ambient pressure [PSI] for Paro
	Logbook: Paro2 air pressure
	During Deployment
	Action: Click "Paro In Water" under Deployment Events.
	Action: Measure curved distance of main cable going around DOM (for at least two DOMs).
	Logbook: Straight (vertical) distance for DOM segment, curved cable distance
	Action: Measure real distance between neighboring DOMs (for every pair) with laser ranger.
	Logbook: DOM#'s, distance
	Action: Put Keller (and one spare) in bucket of water (at near freezing temperature) at least one hour before breakout #15 is reached.
	Note: The Keller is not temperature corrected and must therefore be brought to the temperature of the water in the hole (0-2°C) before the air pressure offset is determined.
ď	Action: Attach Keller at breakout #15.
	ENTER: Keller serial number
	Logbook: Keller serial number
	Action: Click "Keller Attached" under Deployment Events.
	Action: Measure distance between Keller and nearest DOM.
	Estimate distance to <i>bottom</i> DOM by adding $n$ 17-meter segments ( $n$ should be 31 for Keller since nearest DOM is #29).
	ENTER: Distance [m] from Keller to bottom DOM (#60)
	Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60



## IceCube String Deployment Monitoring

B .	Action: Get cable mark reading at Keller.
	Logbook: Cable mark [m] for Keller
Col	Action: Determine Keller air pressure offset before (or just as) Keller hits water.
	ENTER: Ambient pressure [PSI] for Keller
	Logbook: Ambient Keller pressure
T.	Action: Click "Keller In Water" under Deployment Events.
	Action: Get cable mark reading at top DOM.
	Logbook: Cable mark [m]
	Action: Measure well depth as soon as top DOM is under water.
	ENTER: Well depth [m]
	Logbook: Well depth [m], measurement method (laser/tape)
	Between DOM attachment and String Drop
	Action: Lower Setra assembly into hole (after top DOM is at least 50 m under the surface).
	Action: Measure distance between Setra sensor and floor of tower (distance marked on cable).
	ENTER: Distance Setra to floor [m]
, at "	Logbook: Distance Setra to floor
	Action: Measure well depth with Setra system and laser ranger and compare.
	Logbook: Well depth from Setra [m], well depth from laser [m]
	Action: If the two well depth meaurements agree, switch from laser to Setra in monitoring system.

Action: Click "Complete" under Deployment Events.

	During String Drop
	Action: Click "String Drop" under Deployment Events.
	Action: Measure well depth manually (with laser ranger and/or tape measure).
	(if shift lead allows: repeat several times during drop)
	ENTER: Well depth [m]
	Logbook: Well depth, measurement method (laser/tape)
	Action: Read cable marks at regular intervals.
	Logbook: Cable mark [m]; depth readings [m] (Paro, Keller); time
	End of Deployment
**************************************	End of Deployment  Action: Get final pressure readings from Paro and Keller when final depth has been reached.
	Action: Get final pressure readings from Paro and Keller when final depth has been reached.
	Action: Get final pressure readings from Paro and Keller when final depth has been reached.  Logbook: Pressure readings [PSI]; corrected depths [m] (from screen)
	Action: Get final pressure readings from Paro and Keller when final depth has been reached.  Logbook: Pressure readings [PSI]; corrected depths [m] (from screen)  Action: Get final well depth reading (laser and/or Setra).
	Action: Get final pressure readings from Paro and Keller when final depth has been reached.  Logbook: Pressure readings [PSI]; corrected depths [m] (from screen)  Action: Get final well depth reading (laser and/or Setra).  HAS TO BE SIMULTANEOUS WITH FINAL PRESSURE READINGS!

String 73

Name	DOMID	Comments	Position
Schultheiss	TP4Y0035	Droopy	_38
Mamur	TP5P0569	Droopy	42
	TP5P0695	Instead of TP6Y4439	56
Radiophobiaish	TP5P0709	Droopy	34
Great_Rift	TP5P0887	Droopy	18
Baton_Rouge	TP5P0907	Droopy	36
West_Nile_Virusish	TP5P0975	Droopy	
Anthrax	TP5P0981	Droopy	12
Meningitis	TP5P1005	Droopy	
Grunewald	TP5Y0109	Droopy	52
	TP5Y0199	Instead of TP6P1379	28
Gum	TP6P1325		20
Papillon	TP6P1327		10
Stingray	TP6P1329		2
Eagle	TP6P1335		26
Trifid	TP6P1347		50
Eight_burst	TP6P1349		54
Witch_Head	TP6P1351		6
Seven_Spades	TP6P1403		46
Pasur Card	TP6P1409		40
Russian_Bank	TP6P1423		32
Bonnie_And_Clyde	TP6P1739		30
Cool_Hand_Luke	TP6P1743		
Great Escape	TP6P1749		16
From_Russia_With_ Lov	TP6P1751		8
Rudra	TP6Y4277		4
Han_Xiangzi	TP6Y4303		22
Devaki	TP6Y4347		24
Dung Wang Kung	TP6Y4365		48
Girischa	TP6Y4433		14
Mu_Kung	TP6Y4449		44
Chiyou	TP6Y4459		60
Camel	UP4P0272	Droopy	41
Elephant	UP4P0306	Droopy	35
Borasco	UP5P0524	Droopy	27
Hurricane	UP5P0526	Droopy	33
Climatology	UP5P0790	Droopy	31
Japonophilia	UP5P0988	Droopy	
Nebraska	UP5P1016	Droopy	37

Cryptosporidiosis	UP5P1052	Droopy	25
The_Exorcist	UP6P1278	I l	
North_America	UP6P1314		57
Hourglass	UP6P1318		45
Tarantula	UP6P1322		13
Pleiades	UP6P1334	Deploy at top of string	1
Crab	UP6P1336	Deploy at top of string	5
Little_Gem	UP6P1358	_	47
Little_Ghost	UP6P1360		43
Running_Man	UP6P1366		55
Pinochle	UP6P1370		23
Bridge_Card	UP6P1376		53
Nertz	UP6P1426		51
Klondike	UP6P1428		39
Putuoshan	UP6Y4228		21
Narayana	UP6Y4268		19
Laozi	UP6Y4272	Deploy at top of string	3
Kung_Kung	UP6Y4274		9
Vischnu	UP6Y4412		17
Pandavas	UP6Y4430		11
Durga	UP6Y4442		49
	UP6Y4444	Instead of UP6P1266	29
Ho_Tai	UP6Y4458		59
	UP6Y4478	Instead of UP4P0296	15

Remus

AP4P0060 UP5P0794 **58** 7



# String Installation Traveler

Surface Cable#: 73 Length (m): 583 m		Start date: 12/21/06
Surface to DOM Cable#:	C14	Start date: /// / 07

	Process Step	Doc. no. Tech initials Complete		Date Completed	Comments			
1	Visual Inspection of Cables at Pole	9400- 0006-QLP	Mc		no preset			
Surface Cable Assembly Inspection  Pass  Fail  By:  Surface to DOM Cable Assembly Inspection  Pass  Fail  By:								
2	Trench Surface Cable Assembly (SCA)	9400- 0006-QLP	IK	. ,	not present			
3	Install SCA into Surface Junction Box (SJB)	9400- 0006-QLP	MX		not proof			
4	Install SCA into ICL	9400- 0075-PLN	MC	1/4/07	,			
5	Complete IceTop FCU Rower and Data of Installation Procedure	<b>940</b> 0-005- QLP	ZM	12/31/06				
6	Verify Connectivity of IceTop DOMs with Quad Connectivity Tester (QCT)		M	1/4/07				
7	Pre-deployment Inspection Procedure		ME	1/1/07	<del></del>			
8	S2D Cable into SJB installation	9400- 0007-QLP	NC	1/3/07				
9	Wet Connector Testing of Quads		RH	1/9/07	1 wet corn - Q14			
10	QCT Testing of Quads		PH	1/9/07				
11	SJB Final Inspection Complete (Ok to Bury)	9400- 0007-FRM		1/9/07				
12	Handoff to IceCube C &V Team	[	100	1/0/2				



## String Installation Traveler

String QCT and Wet Connector Test Form

String # 73 Name of Tester: Ky	jan H	annetter
--------------------------------	-------	----------

QCT Results
# of DOMs (0, 1, 2) Wet Connector Test Results (micro Amps)

		DOMS (U	, ., <u>-,</u>	1,0100111		est vesuits (IIII	Cro / mips)		
	# of DOMs	# of DOMs	Pass/					Pass/	Recheck Pass/
Quad name	WP0	WP1	Fail	J	L	M	K	Fail	Fail
Q2	2	2	P					b	
Q3	2	2	P					P	
Q4	2	2	ρ					P	
Q5	2	2	P					P	
Q6	2	- 2	P					P	
Q7	ス	2	ρ					P	
Q8	2	2	P					6	
Q9	2	2	P					ę	
Q10	2	2	P					P	
Q11	2	2	P			4		b	
Q12	2	2	P					6	
Q13	2	2	P					b	
Q14	2	2	P			>180/1	>180,4	F	
Q15	2	2	$\rho$					6	
Q16	2	2	P					8	
IceTop Quads			_						
ITQ1	1	1	frank						
ITQ2	/	1	P				71.60		

Service Quads	Device Connected	Verified on	Tech Initials	Comments
Q1				
Q17				
Q18				
Q19				
Q20				